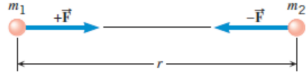
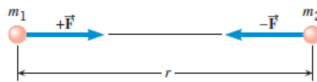
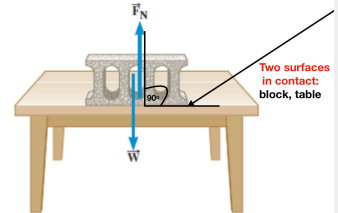
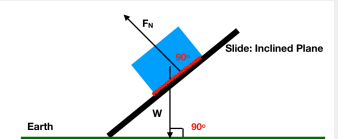
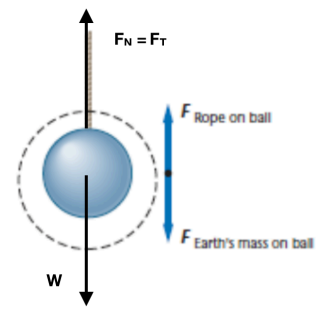
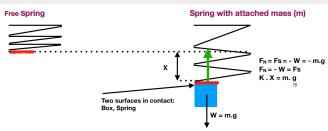
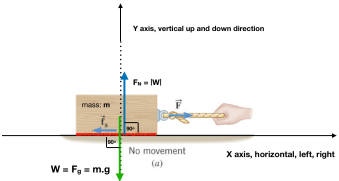
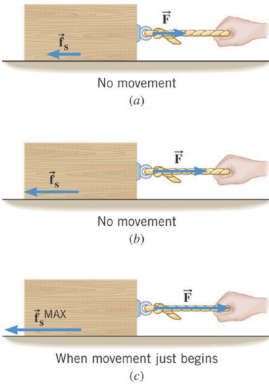
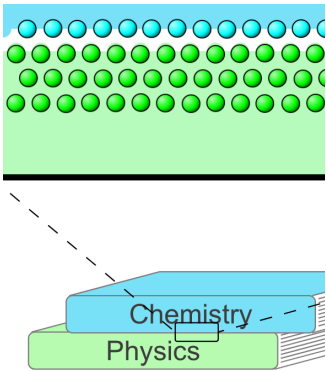
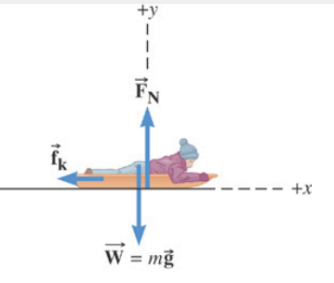


Force	Symbol	Definition	Equation/Formula	Direction	Example
Gravitational <i>illusion</i> It is an effect of space that a mass does.	\vec{F}	It is the force of attraction between 2 objects of non-zero mass and separated by a distance r (between the centers) 	Newton's law of universal gravitation $F = G \frac{m_1 m_2}{r^2}$ F = force G = gravitational constant m_1 = mass of object 1 m_2 = mass of object 2 r = distance between centers of the masses $G = 6.673 \times 10^{-11} \text{Nm}^2/\text{kg}^2$	It is directed along a line joining the centers of particles. 	At rest, on or near the surface of the Earth, the gravitational force equals your Weight $W = F_g = m \times g$ $= m \times 9.8$
Normal Support	F_N	It is the force pushing two surfaces in contact together.	$F_N = -W = -m \cdot g$	<ol style="list-style-type: none"> perpendicular (90°) to the surface of contact opposite direction to the weight and equal weight. W and F_N cancel each other. $W + F_N = 0$	 

Force	Symbol	Definition	Equation/Formula	Direction	Example
Tension	F_T	Is the force acting on a rope when attached to something (pulled by forces acting from opposite sides)	$F_N = F_T = -W$ $= -m \cdot g$ For Equilibrium.	Away from the mass, in the direction of the rope at the point of attachment.	<p>Ball hanging from rope</p> 
Spring	F_s	Stress is proportional to strain	$F_s = K \cdot x$ $F_s = F_N = -W$ $K \cdot x = m \cdot g$	Opposite to the Weight. Opposite to the direction of the stretch.	

Force	Symbol	Definition	Equation/Formula	Direction	Example
<p>Static Frictional</p> <p>(Not in motion, rest, no movement)</p>	f_s	<p>Force:</p> <ol style="list-style-type: none"> between the particles of 2 surfaces in contact, not in motion (rest) attempt to move. Resists the force to move (slide) the object. Object only moves when the applied force $F > f_s \text{ max}$ 	$f_s = (\text{coefficient of static friction}) F_N$ $f_s = \mu_s F_N$ $f_s = \mu_s m \cdot g$	<p>fs</p> <ol style="list-style-type: none"> Parallel to the surface of contact Opposite to the direction of sliding. 	<p>Object only moves when the applied force (F) exceeds the maximum static frictional force ($f_s \text{ max}$)</p> <p>$F > f_s \text{ max}$</p> 
					

Force	Symbol	Definition	Equation/Formula	Direction	Example
Kinetic Frictional Motion, Moving, Sliding,	\mathbf{f}_k	Force: 1) between the particles of 2 surfaces in contact, 2) in motion (moving, sliding) 3) Resists the force to slide the object.	$f_k = (\text{coefficient of kinetic friction}) F_N$ $f_k = \mu_k F_N$ $f_k = \mu_k m \cdot g$	1) Parallel to the surface of contact 2) Opposite to the direction of sliding.	 <p>The diagram shows a person sliding on a horizontal surface. A coordinate system is defined with the x-axis pointing to the right and the y-axis pointing upwards. Three force vectors are shown: a normal force vector \vec{F}_N pointing vertically upwards from the center of the person, a weight vector $\vec{W} = m\vec{g}$ pointing vertically downwards from the center, and a kinetic friction force vector \vec{f}_k pointing horizontally to the left, parallel to the surface.</p>

$$W = m \cdot g$$

Weight

Perpendicular to the center of the Earth

$$F_N = -W = m \cdot g$$

Two surfaces in contact

Normal Force, support

Perpendicular to contact

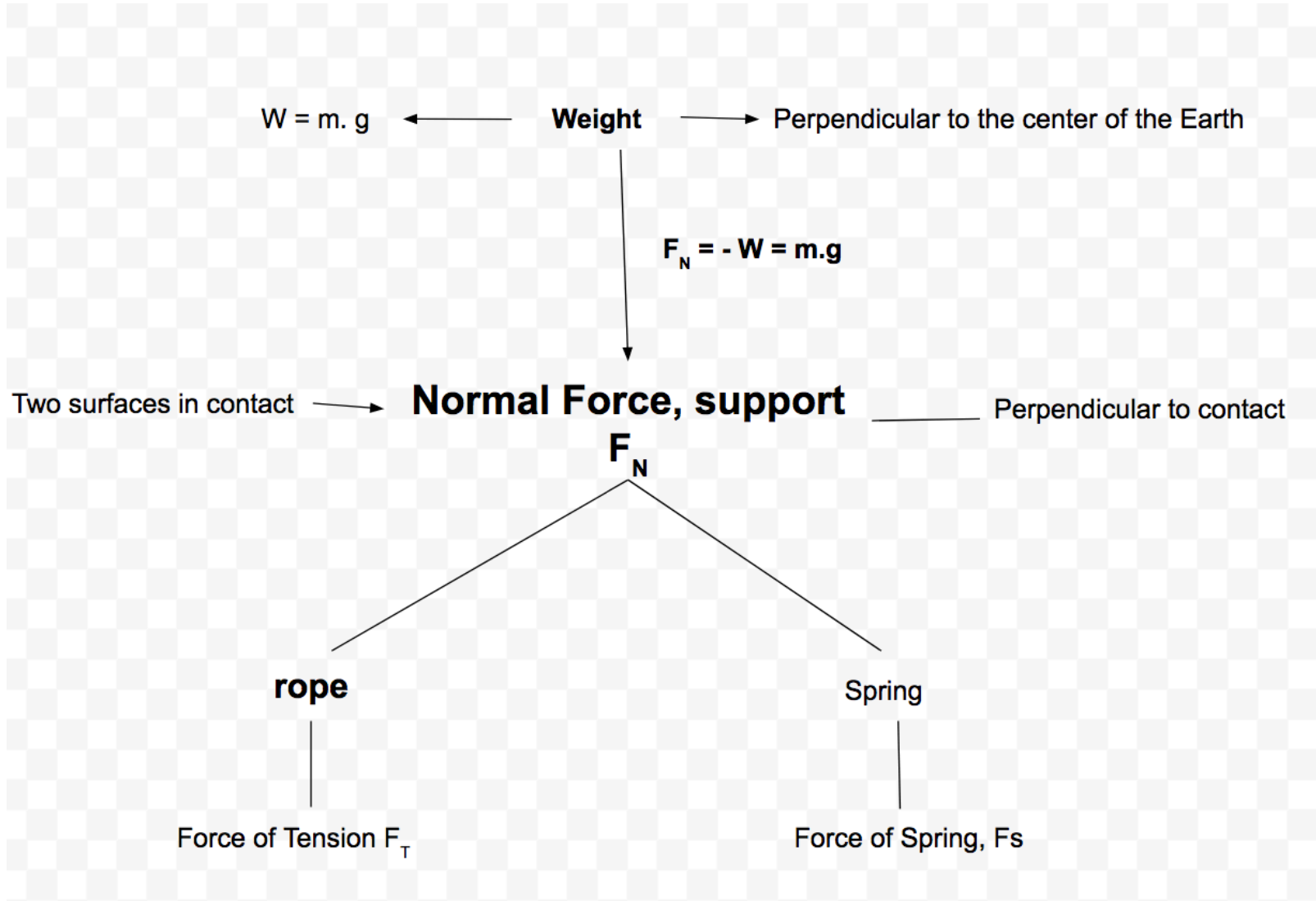
F_N

rope

Spring

Force of Tension F_T

Force of Spring, F_s



$$W = F_g = m \cdot g$$

Weight, $F_g = W$

Perpendicular to Earth

$$F_N = -W = m \cdot g$$

Two surfaces in contact

Normal (support, 90°)
Force, F_N

Perpendicular to surface of contact
Opposite to weight

Rope
Tension Force, F_T

Spring
Force of Spring, F_s

Lorem Ipsum

Lorem Ipsum

Lorem Ipsum

Lorem Ipsum

$$W = F_g = m \cdot g$$

Weight, W, F_g

Perpendicular to Earth

$$F_N = -w = m \cdot g$$

F_N and w cancel each other

2 surfaces in contact

**Normal (90° support)
Force, F_N**

Perpendicular to contact surface
Opposite to weight

Rope, F_T

Spring, F_s

Lorem Ipsum

Lorem Ipsum

Lorem Ipsum

Lorem Ipsum

$$W = F_g = m \cdot 9.8$$

Weight, W, F_g

Perpendicular to Earth

$$F_N = -W = m \cdot g$$

F_N and W cancel each other

2 surfaces in contact

**Normal (90°, Support)
Force, F_N**

Perpendicular to surface of contact
Opposite to weight (W)

Rope

Tension Force, F_T

Spring

Force of Spring, F_s

Opposite to W
At the point of
attachment

$$F_T = -W$$

$$F_s = -W$$
$$K \cdot X = m \cdot g$$

$$F_s = K \cdot X$$

$$W = F_g = m \cdot g$$

$$g = 9.8 \text{ m/s}^2 \text{ or N/Kg}$$

Weight, W, F_g

Down perpendicular to Earth

$$F_N = -W$$

F_N and W cancel each other

2 surfaces in contact

Normal (90°, Support)
Force, F_N

Perpendicular to contact surface
Up and opposite to weight

Rope
Tension Force (F_T)

Spring
Spring Force (F_s)

Opposite
Direction of stretch

Opposite to W at the
point of attachment

$$F_T = W$$

$$F_s = W$$
$$K \cdot X = m \cdot g$$

$$F_s = K \cdot X$$